# The Usual Derivation of Neural Net Backpropagation 

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This treatment mostly follows http://www.doc.ic.ac.uk/~nd/surprise_96/journal/vol4/ cs11/report.html. I used the open source computer algebra package Maxima (http:// maxima.sourceforge.net) to do and check some of the math.

Consider a neuron that looks like this:


We start with the axiomatic definitions. We will assume that all inputs to a neuron are in the interval $[-1 \ldots 1]$ and that the output will be in the same range. Our squashing function is the symmetric version of the sigmoid. Our first goal is to try to pick weights to minimize the mean squared error $E$ between the desired output $y$ and the actual output $\hat{y}$.

$$
\begin{align*}
x_{i}, w_{i} & \in[-1 \ldots 1]  \tag{1}\\
h & =\sum_{i} w_{i} x_{i}  \tag{2}\\
s & =\frac{e^{h}-1}{e^{h}+1}  \tag{3}\\
\hat{y} & =s \circ h  \tag{4}\\
E(y, \hat{y}) & =\frac{1}{2}(\hat{y}-y)^{2} \tag{5}
\end{align*}
$$

We now compute a couple of derivatives that will be interesting in error analysis. Note how the derivative of the sigmoid squashing function $s$ is itself a simple function of that sigmoid. This is convenient in the implementation, since it means that we can use a single routine for both training and classification.

$$
\begin{align*}
E_{y} & =\frac{\partial E}{\partial \hat{y}}  \tag{6}\\
& =\hat{y}-y  \tag{7}\\
E_{\hat{y}} & =\frac{\partial \hat{y}}{\partial h}  \tag{8}\\
& =\frac{\partial s(h)}{\partial h}  \tag{9}\\
& =\frac{\frac{\partial}{\partial h}\left(e^{h}-1\right) \cdot\left(e^{h}+1\right)-\left(e^{h}-1\right) \cdot \frac{\partial}{\partial h}\left(e^{h}+1\right)}{\left(e^{h}+1\right)^{2}}  \tag{10}\\
& =\frac{e^{h}\left(e^{h}+1\right)-\left(e^{h}-1\right) e^{h}}{\left(e^{h}+1\right)^{2}}  \tag{11}\\
& =\frac{e^{h}\left(e^{h}+1-e^{h}+1\right)}{\left(e^{h}+1\right)^{2}}  \tag{12}\\
& =\frac{2 e^{h}}{\left(1+e^{h}\right)^{2}}  \tag{13}\\
& =\frac{1}{2}\left(1-s^{2}(h)\right)  \tag{14}\\
& =\frac{1}{2}\left(1-\hat{y}^{2}\right) \tag{15}
\end{align*}
$$

Next, we compute the error due to weight $w_{i}$ and due to input $x_{i}$. We use the chain rule on the previously calculated derivatives.

$$
\begin{align*}
E_{w_{i}} & =\frac{\partial E}{\partial w_{i}}  \tag{16}\\
& =\frac{\partial E}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial h} \cdot \frac{\partial h}{\partial w_{i}}  \tag{17}\\
& =E_{y} \cdot E_{\hat{y}} \cdot \frac{\partial h}{\partial w_{i}}  \tag{18}\\
& =(\hat{y}-y) \cdot \frac{1}{2}\left(1-\hat{y}^{2}\right) \cdot x_{i}  \tag{19}\\
E_{x_{i}} & =\frac{\partial E}{\partial x_{i}}  \tag{20}\\
& =\frac{\partial E}{\partial h} \frac{\partial h}{\partial x_{i}}  \tag{21}\\
& =(\hat{y}-y) \cdot \frac{1}{2}\left(1-\hat{y}^{2}\right) \cdot w_{i} \tag{22}
\end{align*}
$$

At this point, we can use $E_{w_{i}}$ to adjust the weights, and then use $E_{x_{i}}$ to find error terms for the prior; that is, for the outputs from the previous network layer.

Another legitimate choice would have been to have chosen to have $x$ and $y$ in the range $[0 \ldots 1]$. This is the more common choice in the literature. The math is the same, except that we now use
a slightly different sigmoid for our squashing function, which of course has a slightly different derivative.

$$
\begin{align*}
x, y & \in[0 \ldots 1]  \tag{23}\\
s(h) & =\frac{1}{1-e^{-h}}  \tag{24}\\
E_{\hat{y}} & =\frac{\partial \hat{y}}{\partial h}  \tag{25}\\
& =\frac{\partial s(h)}{\partial h}  \tag{26}\\
& =\frac{\partial}{\partial h}\left[\left(1-e^{-h}\right)^{-1}\right]  \tag{27}\\
& =-\left(1-e^{-h}\right)^{-2} \cdot \frac{\partial}{\partial h}\left(1-e^{-h}\right)  \tag{28}\\
& =\frac{-e^{-h}}{\left(1-e^{-h}\right)^{2}}  \tag{29}\\
& =\hat{y}(1-\hat{y}) \tag{30}
\end{align*}
$$

The adjustment to equations 19 and 22 is presumably obvious.

