

Trees, Graphs and Graph Operations

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February 2, 2016

Trees

A graph is a data structure made from vertices and edges. An edge notionally connects two vertices.

$$\begin{array}{l} [VERTEX] \\ EDGE == VERTEX \times VERTEX \end{array}$$

A tree is a special case of a graph: it has exactly n vertices and $n - 1$ edges, and is connected.

<i>Tree</i>
<i>vertices</i> : $\mathbb{P} VERTEX$ <i>edges</i> : $\mathbb{P} EDGE$
$\# vertices = \# edges + 1$ $edges^* = vertices$

As a consequence of this definition, there can be no cycles in a tree.

We can think of trees as directed or undirected, but normally undirected. In a directed tree, the edges are read left-to-right: in an undirected tree, they are considered symmetric, or are considered to run in both directions.

<i>UndirectedTree</i>
<i>Tree</i>
$edges = edges \sim$

A rooted tree has a distinguished root vertex. We refer to a vertex as the parent of a neighbor (child) if it is closer to the root of the tree.

<i>RootedTree</i>
<i>Tree</i> <i>root</i> : $VERTEX$
$root \in vertices$

Binary Trees

A binary tree is a rooted tree such that the root vertex has exactly two neighbors, and all other vertices have three. We usually draw these “upside-down” for convenience.

Graphs

A graph is the general case where there can be cycles.

Graph

vertices : \mathbb{P} VERTEX

edges : \mathbb{P} EDGE

Again connected, directed, undirected, rooted etc are defined in the obvious way.

Labeling

The edges and/or vertices of a graph may have labels attached. The labels can be thought of as given by a labeling function, in the fashion we are used to.

Graph Representation

There are actually multiple standard ways to represent a graph for modeling or computation:

- Edge List
- Adjacency List
- Adjacency Matrix

Graph Algorithms

Some standard algorithms are useful for manipulating graphs.

- Depth-First Search
- Breadth-First Search
- Transitive Closure